

## problem sheet 6

discussion: week of Monday, 11.11.2019

**6.1.** Consider quadrature rules  $Q^{2D}$  on the square  $S = [0, 1]^2$ .

- a) Show: the midpoint rule  $Q(F) = F(0.5, 0.5)$  is exact for polynomials of the form  $F(x, y) = a + bx + cy$ .
- b) Given  $p \in \mathbb{N}_0$ , give a quadrature formula  $Q^{2D}$  that is exact for polynomials of the form  $F(x, y) = \sum_{i,j=0}^p a_{ij} x^i y^j$ .

**6.2.** Develop an adaptive algorithm for the integration of functions over the rectangle  $[a_x, b_x] \times [a_y, b_y]$ . Base your algorithm on the midpoint rule, i.e.,  $Q_{[a,b] \times [c,d]}(f) = (b-a)(d-c)f((a+c)/2, (b+d)/2)$ . *Hint:* adapt the ideas of the 1d-adaptive algorithm of Problem 4.4. Test your adaptive algorithm for the integration over  $[0, 1]^2$  of the following functions:

$$f_1(x, y) = x^2 \quad \text{and} \quad f_2(x, y) = \begin{cases} 0 & x < y \\ 1 & x \geq y \end{cases}$$

Use the tolerances  $\tau = 2^{-i}$ ,  $i = 0, \dots, 15$ , and make a convergence plot (quadrature error versus tolerance) in **loglog** scale.

**6.3.** Consider the function

$$\varphi(x) = \sqrt{x+1} - \sqrt{x}$$

- a) Is the evaluation of  $\varphi$  well-conditioned for large  $x$ ? Consider relative conditioning.
- b) Formulate a stable numerical realization of  $\varphi$  (*Hint:* You may use that a stable realization of  $\sqrt{\cdot}$  is available.)

**6.4.** The sequence  $u_k$ ,  $k = 0, 1, \dots$ , given by

$$u_1 := 2, \quad u_{k+1} = 2^k \sqrt{2 \left( 1 - \sqrt{1 - (2^{-k} u_k)^2} \right)} \tag{1}$$

converges to the number  $\pi = 3.1415\dots$

- a) Compute (in `matlab/python`) the first 30 members of the sequence and the absolute error  $|\pi - u_k|$ . When is the error minimal?
- b) Explain why you should expect that the error grows for  $k \geq k_0$  for some  $k_0$ . *Extra Problem:* Assume that in exact arithmetic the error is  $|u_k - \pi| \approx 2^{-2k}$ . Use this to show that the minimal achievable error is reached for  $k \approx 17$ .

**6.5.** (Aitken  $\Delta^2$  extrapolation)

- a) The Aitken  $\Delta^2$  method can be used to accelerate the convergence of a sequence  $(x_n)_n$  that converges to  $x_\infty = \lim_{n \rightarrow \infty} x_n$ . To that end, assume that the sequence  $(x_n)_n$  has the form

$$x_n = x_\infty + Cq^n \tag{2}$$

with (unknown)  $x_\infty$ ,  $C$ ,  $q \in (0, 1)$ . Give a formula that “extrapolates” the sought limit  $x_\infty$  from 3 successive sequence members  $x_n, x_{n+1}, x_{n+2}$  by assuming that all 3 values satisfy (2). Proceeding in this way for every  $n$  produces a new sequence  $(\tilde{x}_n)_n$  that (sometimes) converges faster to  $x_\infty$  than the original sequence. Apply this method to the sequence  $(u_k)_k$  of Problem 6.4 to get a new sequence of improved approximations to  $\pi$ . What is the best possible error?

- b) Suppose you don’t know the limit  $\pi$  of the sequence  $(u_k)_k$ . How can you estimate the errors of the approximations  $u_k$ ? Can you formulate a sensible stopping criterion for the iteration (1)?